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OB

1-PLC



- Explain the difference between classic control and PLC
- Explain the purpose of a PLC Interface Modules (IM) and Expansion modules SM, CM, PS and describe how it is connected in the PLC Rack
- Using practical examples, explain the Wiring of Digital Input/Digital Output and Analog Input/Analog Output modules
- List and explain all methods of connecting the PLC to the programming computer
- Explain how to configure the PLC Hardware, Rack, Power Supply, CPU and Digital Input(DI), Digital Output(DO), and Analog Input (AI) in TIA Portal
- Explain how to use the PLC Simulator
- Explain the concept of scan cycle and operation modes in PLC
- Explain watch and force table and List the 3 programming languages available in Step 7
- Demonstrate how to populate ladder logic rungs and address Bit Loginstructions on each rung using Absolute and Symbolic Addressing
- Explain the purpose of the Latch and Set , Reset instructions, RS and SR Flip-flops and demonstrate the proper use of each
- Demonstrate how to use markers and POS,NEG edges
- Demonstrate how to use all types of STEP 7 timers and counters
- Demonstrate how to use all types of SIMATIC timers and counters
- Explain the Numbering System terms Decimal, Binary, and BCD
- Explain Data Types
- List and explain the operation of all CMP instructions
- Write a ladder logic program using Math instructions
- Perform PLC Data Numbering Type conversions



1-PLC

Level 2

- Write a ladder logic program using Move instructions
- Write a ladder logic program using Shift and Rotate Instructions
- Explain the operation of the following Logic Gates: AND, OR, XOR, and Invert
- Explain the purpose of a Jump Instruction
- Explain what a Watchdog Timer is and describe an example of where it can be used
- Explain what an Infinite Loop Error is
- Demonstrate pulse generation using timers and the CPU Clock
- Configure a function (FC) to perform a task or calculation such as volume in a tank
- Configure a Function Block (FB) to perform a repetitive task
- Define and configure a Data Block (DB)
- Understading structures, arrays and UDT
- Configure and describe the most common types of OBs and when to use them (OB1, OB100, OB30, OB20, OB10, OB 80, OB82, OB

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2-HMI

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- 1. WinCC Comfort/Advanced HMI System Overview
- 2. Project Creation & Communication Setup in TIA Portal
- 3. Screen Design (screens, pop-up screens and templates).
- 4. Multi-Language Setup
- 5. Basic elements and Library Utilization
- 6. Navigating through the process pictures
- 7. User administration
- 8. Alarm display, alarm logging, alarm configuration
- 9. Tag logging, trend configuration, trend display
- 10. Recipe Management
- 11. Faceplates for reuse and centralized modification of graphics blocks
- 12. (C) Working with Layers
- 13. (C) Animation (rotation / vertical movement / text & graphic list)
- 14. (C) How to Add trends f(t) & f(x) / value table/ table view
- 15. Schedualed Tasks
- 16. VB Scripting example
- (C) Common with SCADA





3-SCADA Level 1

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- 1. SCADA introduction
- 2. Buttons and I/o field
- 3. Internal and external Scaling
- 4. Animation (rotation / vertical movement / text & graphic list)
- 5. How to Add trends f(t) & f(x) / value table/ table view
- 6. Recipe management
- 7. User administration
- 8. Printing reports
- 9. Create Faceplate
- 10. Working with Layers
- 11. (C)Alarm display, alarm logging, alarm configuration
- 12. (C)Screen Design (screens, pop-up screens and templates).

10/22/2015 2:55:27 PM (956) ✓ ExampleDP_Arg1. 44.8042

ExampleDP_Arg2. 71.9901

rend Ruler Values

ExampleDP Arg1

14:55:20 14:55:40 14:56:00 14:56:20 14:56:40 14:57:00 14:57:20 14:57:40 14:58:20

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44.8042

13. (C)Multi-Language Setup

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- 14. (C)Schedualed Tasks
- (C) Common with HMI

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Visual Studio

1-Learn how to program By C#

- Get started(Syntax/ Output/ Comments/ Variables/ Data Types / Type Casting / User Input / Operators / math/ Strings/ Booleans/ If ... Else / Switch / While Loop / For Loop / Break and Continue / Arrays)
- Methods (Method Parameters/ Method Overloading)

3-SCADA Level 2

Classes(OOP / Classes and Objects/ Class Members/ / Constructors)

2-building SCADA using C

Connecting with real PLC S7-1200

3-explain Data Base and all types of SQL Commands in SQL server

DDL (create / drop / alter /truncate) DML (insert / update / delete) DCL (grant / revoke)

TCL (commit / roll back / save point)

DQL (select)

Microsoft[®] SQL Ser

4- linking C# with SQL Server to create final program

Read / Write Data (Analog / digital) in SQL Database with example Create exe App

Projects and examples



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4- Communication

1-fundamentals (Transmission Methods - Network topology - Transmission Media - OSI Model - network devices -Error control) 2-Modbus RTU.

- a-Connecting s7-1200 with P18D via modbus RS485 b-Connecting s7-1200 with kinco servo via modbus RS485
- 3-Foundadion Fieldbus.
- a. 1-Basics of FF
- b. 2-architecture of H1 Vs OSI.
- c. 3-architecture OF HSE Vs OSI.
- d. 4-Diffrenece between H1 and HSE according to physical layer
- e. 5-Design of FF segment
- f. 6-FF Terminator.
- g. 7-FF power supply&Fielbus Barrier.&FF Topologies.& FF Grounding.

4-Profibus

- a. OSI & PROFIBUS (DP-FMS-PA)
- Difference between Centeralized and Decenteralized
- c. Profibus_DP Design introduction
- d. PROFIBUS-DP Addressing
- e. Bus Termination.
- f. PROFIBUS-DP cable specs.
- g. GSD files.
- h. Communicatopn port parameters
- i. ET200.
- j. Connecting PLC with ET200 via PROFIBUS-DP
- k. Connecting PLC s7-400 with PLC s7-300 via R

5-S7-Communication.

- 6-USS communication
 - a- Connecting s7-1200 with SINAMICS V20 via USS

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5- Servo motion

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- 1. programming digital inputs and outputs of dervo drive ASDA-B2
- 2. Explain Servo in position mode with plc + application
- 3. Explain Servo in velocity mode + application
- 4. Explain Servo in torque mode + application
- 5. Explain Servo in dual mode + application

All lessons contain More than 20 real Application